python main.py --dataset data/TOY10/cercle --losses="[]" --scheduler\_params="{'target\_loss': 'LogBarrierLoss', 'mu': 1.1}" --n\_epoch 20 --losslist "['compactness', 'distance', 'size', 'centroid', 'sizeCE', 'OCE','crossentropy','length', 'bounding\_box', 'size\_bounding\_box', 'ratio\_bounding\_box']"

python main\_without\_gt.py --dataset data/capillaires --losses="[]" --scheduler\_params="{'target\_loss': 'LogBarrierLoss', 'mu': 1.1}" --n\_epoch 20 --losslist "['emptiness','height\_width\_bounding\_box', 'ratio\_height\_widthbounding\_box', 'sizewgt']"

python gen\_toy\_2.py --dest "data/TOY10" -n 10 10 -wh 256 256 -r 32